

Prerekvizity pro instalaci verze 4.5.32

- **AUBOPE Version:** V4.0.2 nebo vyšší
- **Interface board Version:** V3.0.0 nebo vyšší
- **Joint software Version:** V3.0.2 nebo vyšší

The screenshot displays the AUBO software interface. At the top, there is a navigation bar with tabs for Robot Teaching, Programming, Settings, Extensions, System Info, and About. The 'About' tab is selected, showing the following information:

- Version 4.5.0_Foreign** (highlighted in red) AUBOPE Version
- Built on Jun 06 2019 at 11:07:21
- Copyright(c) 2015 - 2019
- <http://aubo-robotics.cn>

Below this, the 'Hardware version information' section is visible, with the following details:

Revision:	V3.2.9	Interface board Version
Slave Version:	V3.1.0	
Extend IO Version:	V1.1.2	
ManuID:	AUBO	
Joint Type:	I-5	
Joint(1) hardware version:	3	
Joint(1) software version:	3.0.4	Joint software version
Joint(2) hardware version:	3	
Joint(2) software version:	3.0.4	
Joint(3) hardware version:	3	
Joint(3) software version:	3.0.4	
Joint(4) hardware version:	2	
Joint(4) software version:	3.0.4	
Joint(5) hardware version:	2	
Joint(5) software version:	3.0.4	
Joint(6) hardware version:	2	
Joint(6) software version:	3.0.4	
Tool hardware version:	1	
Tool hardware version:	1.2.0	
Base hardware version:	8	
Base software version:	2.3.0	
Interface Board ID:	64 4E CF D9	
Joint(1) ID:	2C F7 55 2A	
Joint(2) ID:	53 D5 B6 08	
Joint(3) ID:	89 A1 B4 02	
Joint(4) ID:	10 A0 E2 2E	

At the bottom of the interface, there are buttons for 'Zero Pose' and 'Init Pose', a speed display of '0.00 (mm/s)', a timestamp of '2019-10-22 11:30:52', a speed slider set to '50%', and a 'Help' button.