

Prerekvizity pro instalaci verze 4.5.24

- **AUBOPE Version:** V4.3.0 nebo vyšší
- **Interface board Version:** V3.2.0 nebo vyšší

The screenshot displays the AUBO software interface. At the top, there is a navigation bar with the AUBO logo, the user name 'admin', and a power icon. Below this is a menu with options: Robot Teaching, Programming, Settings, Extensions, System Info, and About. On the left side, there are buttons for About, Version, and Disclaimer. The main content area shows the AUBO logo and the text 'Version 4.5.0_Foreign AUBOPE Version', 'Built on Jun 06 2019 at 11:07:21', 'Copyright(c) 2015 - 2019', and the website 'http://aubo-robotics.cn'. Below this is a section titled 'Hardware version information' containing a list of system parameters. The 'Revision:' parameter is highlighted with a red box and labeled 'Interface board Version'. At the bottom of the interface, there are buttons for 'Zero Pose' and 'Init Pose', a speed display of '0.00 (mm/s)', a timestamp '2019-10-22 11:30:52', a speed slider set to '50%', and a 'Help' button.

admin

Robot Teaching Programming Settings Extensions System Info About

About
Version
Disclaimer

Version 4.5.0_Foreign AUBOPE Version
Built on Jun 06 2019 at 11:07:21
Copyright(c) 2015 - 2019
<http://aubo-robotics.cn>

Hardware version information

Revision:	V3.2.9	Interface board Version
Slave Version:	V3.1.0	
Extend IO Version:	V1.1.2	
ManulD:	AUBO	
Joint Type:	I-5	
Joint(1) hardware version:	3	
Joint(1) software version:	3.0.4	
Joint(2) hardware version:	3	
Joint(2) software version:	3.0.4	
Joint(3) hardware version:	3	
Joint(3) software version:	3.0.4	
Joint(4) hardware version:	2	
Joint(4) software version:	3.0.4	
Joint(5) hardware version:	2	
Joint(5) software version:	3.0.4	
Joint(6) hardware version:	2	
Joint(6) software version:	3.0.4	
Tool hardware version:	1	
Tool hardware version:	1.2.0	
Base hardware version:	8	
Base software version:	2.3.0	
Interface Board ID:	64 4E CF D9	
Joint(1) ID:	2C F7 55 2A	
Joint(2) ID:	53 D5 B6 08	
Joint(3) ID:	89 A1 B4 02	
Joint(4) ID:	10 A0 E2 2E	

Help

Zero Pose Init Pose 0.00 (mm/s) 2019-10-22 11:30:52 Speed: 50%